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Abstract. The technique of numerical inversion of the Laplace transform is applied to solve the population balance equation (PBE). The model considers the dispersed phase systems in which nucleation and heterogeneous condensation are present. The studied phenomena model corresponds to a nonlinear integro-partial-differential equation. Test cases are solved considering two different collision mechanisms, the first-order removal mechanism and the effect of simultaneous coagulation and growth. Numerical results are compared with the analytical solution and with the literature. Based on these results, the technique applied in this work demonstrates to be a tool to solve problems in particulate systems, particularly for aerosol modeling where coagulation is the most important inter-particle mechanism affecting the size distribution.

Keywords: Aerosol modeling, Numerical inversion of the Laplace transform, Particle size distribution.

1. Introduction

Dispersed phase systems are the subject of interest in many chemical engineering processes such as fluidized beds [1, 2], droplet dispersions [3], crystallization [4, 5], precipitation [6], liquid-liquid extraction [7, 8], polymerization [9-11], granulation [12, 13], and colloid chemistry [14, 15]. In all such applications, micro-scale processes such as nucleation, particle growth through collisions and coalescence with other particles (coagulation), and agglomeration of particles are present [16, 17]. The modeling approach well suited for systems where nucleation, growth, and aggregation occur is the concept of population balance (PB). In mathematics, the PBE is a strong non-linear equation with the same mathematical structure as Boltzmann's transport equation which corresponds to a nonlinear integro-partial-differential equation and an exact analytical solution is rarely analytically tractable [18, 19] with very few analytical solutions for some ideal cases [20].

Precipitation and crystallization are widely studied problems in modern chemical engineering, which are used to separate and purify solid materials. Several phenomena are involved, such as cooling rate, thermal history, mixing performance, impurities, crystallizer volume/geometry, mixing at various scales, nucleation, crystal growth, aggregation, and breakage [21, 22]. Particle size and size distribution are key to the physical properties of catalysts and other particles or aggregates in nature. Nearmonodisperse ($\leq \pm 15\%$) if not narrower, approaching monodisperse particle size distributions (PSDs) are highly desirable. Because of this, mechanism-based, rational control of particle size and PSDs is a longstanding goal in nano and other-particle science [23]. Crystallization, which is a widely used solid-liquid separation technique, has three general operation modes, i.e., evaporation of the solvent, cooling down of the solution, and adding antisolvent into the solution. For a practical application, crystal size distribution (CSD) is an important quality index of the prepared particles, which directly influences the product properties such as filtration rate, bioavailability, and dewatering rate [24]. Thus, controlling the CSD of the particles becomes important and challenging work [25].

The population balance equation (PBE) has become a fundamental equation in the study on aerosol dynamical processes, where the most important phenomena are nucleation and heterogeneous condensation, with subsequent coagulation and breakup [26]. Because of the strong dependence of aerosol properties such as scattering, and Brownian coagulation, to predict the aerosol properties, it is desirable to understand in as much detail as possible the inter-particle mechanism affecting the size distribution. The size distribution of an aerosol is described by the number density function of the particles, which is a transient multidimensional equation and can include, volume, surface area, or chemical composition [27], and is governed by a general PBE. Numerical methods must be necessary for simulations of atmospheric aerosol dynamics including turbulence transport and



dispersion. However, many analytical solutions for population balance are applied in atmospheric research-related literature [22] and are valuable for the description of the phenomena in more complex particle systems situations [16, 18, 19].

The Laplace transform operation is an excellent alternative to solve the PBE. The PBE is a nonlinear integro-partial-differential equation and the Laplace transform can handle the integral term in PBE directly. Furthermore, the volume domain can be transformed into the Laplace transform domain simplifying the equation. Nevertheless, there is no unique method to perform the numerical inversion of the Laplace transform and the best method must be verified for each studied phenomenon. On this point, the objective of this work is to solve a general model for the size distribution of PBE by applying the Laplace transform inversion to demonstrate the possibility of the numerical inversion for PBE applications enabling future research using the same methodology. An analytical comparison of the present results with solutions presented in the literature for simplified situations is performed to verify the method solution. Moreover, the results obtained in this work are appropriate for characterizing the dynamic behavior of any system of particles in which the phenomena of condensation with subsequent coagulation are present such as crystallization [4, 5] and precipitation [6] processes.

2. Analysis

The general population balance equation of a spatially and chemically homogeneous particulate system considering the mechanisms of agglomeration of the small particles into larger particles (coagulation), condensation and the adding material through the fluid phase (sink or loss of material), Fig. 1, is described in terms of the continuous particle size distribution, n(v,t) [28-31]:

$$\frac{\partial n(v,t)}{\partial t} = -\frac{\partial}{\partial v} [I(v,t)n(v,t)] + \frac{1}{2} \int_{0}^{v} \beta(v-\tilde{v},\tilde{v})n(v-\tilde{v},t)n(\tilde{v},t)d\tilde{v} - n(v,t) \int_{0}^{\infty} \beta(v,\tilde{v})n(\tilde{v},t)d\tilde{v} + S[n(v,t),v,t]$$
(1.a)

where t is the time, v is the particle volume, I(v,t) is the growth/loss and I(v,t) > 0 represents the surface growth rate whereas I(v,t) < 0 the evaporation loss rate, S is the nucleation rate including the possible addition of new particles in the system. The integral source term accounts for agglomeration following the continuous counterpart of the Smoluchowski equation where $\beta(v - \tilde{v}, \tilde{v})$ represents the coagulation kernel function for particles of volume v and \tilde{v} . The initial and boundary conditions for Eq. (1.a) are usually given as:

$$n(v,0) = \frac{N_0}{v_0} e^{-v/v_0}; \quad n(0,t) = 0$$
(1.b,c)

where N_0 and v_0 are the initial total particle number and the initial total particle volume respectively. The first term on the right side of Eq. (1.a) represents the growth rate of change of a particle size distribution n(v,t) by mass transfer to individual particles. The second term corresponds to the production of particles by coagulation of the appropriate combinations of smaller particles by the collision of two particles of volume $\beta(v - \tilde{v}, \tilde{v})$ and \tilde{v} to form a particle of volume v (assuming conservation of volume during coagulation). The third term corresponds to the loss of particles with collisions with all available particles. The last term is the net rate of the addition of fresh particles into the system. Equation (1) provides a wide variety of physical contexts, similar to polymerization, atmospheric dynamics of aerosols, crystallization and precipitation, and biological population dynamics.

2.1 Solution methodology via Laplace transform technique

For solving the mathematical model given by the integro-partial-differential Eq. (1), the Laplace transform with numerical inversion was employed. Therefore, for this purpose, four test cases were considered (Table 1) and compared with the finite element method in the literature [29], namely, i) test-case 1: constant aggregation coefficient $\beta(v, \tilde{v}) = \beta_0$ and no condensation and source terms I(v,t) = S[n(v,t),v,t] = 0; ii) test-case 2: linear aggregation coefficient $\beta(v, \tilde{v}) = \beta_1(v + \tilde{v})$ and no condensation and source terms I(v,t) = S[n(v,t),v,t] = 0, iii) test-case 3: constant aggregation coefficient $\beta(v, \tilde{v}) = \beta_0$ with linear growth rate $I(v,t) = \sigma v$ and no source terms, and iv) test-case 4: linear aggregation coefficient $\beta(v, \tilde{v}) = \beta_1(v + \tilde{v})$ no condensation and particle removal rate $S[n(v,t),v,t] = -R_0n(v,t)$.



Fig. 1. Schematic configuration of the considered structure/system.

Table 1. Test Cases for t	ne studied phenomena.
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Test Case	Aggregation $\beta(v, \tilde{v})$	Condensation $I(v,t)$	Source Term S[n(v,t),v,t]	
1	β_{0}	-	-	
2	$\beta_1(\mathbf{v}+\tilde{\mathbf{v}})$	-	-	
3	β_{0}	σv	-	
4	$\beta_1(v + \tilde{v})$	-	$-R_{o}n(v,t)$	



2.1.1 Test-case 1

The Laplace transform procedure of Eq. (1.a), to remove the independent variable v, for the test-case 1 is now established as follows:

$$\mathcal{L}\left[\frac{\partial n(v,t)}{\partial t}\right] = \frac{\partial \overline{n}(s,t)}{\partial t}; \ \mathcal{L}\left[\frac{\beta_0}{2}\int_0^v n(v-\tilde{v},t)n(\tilde{v},t)d\tilde{v}\right] = \frac{\beta_0}{2}\overline{n}^2(s,t); \ \mathcal{L}\left[\beta_0n(v,t)\int_0^\infty n(\tilde{v},t)d\tilde{v}\right] = \beta_0M_0(t)\overline{n}(s,t)$$
(2.a-c)

where, $\overline{n}(s,t) = \mathcal{L}[n(v,t)]$. Therefore, the transformed differential equation for this case, from the results of Eqs. (2), together with the transformed initial condition, are written as:

$$\frac{\partial \overline{n}(\mathbf{s},t)}{\partial t} + \beta_0 M_0(t) \overline{n}(\mathbf{s},t) = \frac{\beta_0}{2} \overline{n}^2(\mathbf{s},t)$$
(3.a)

$$\overline{n}(s,0) = \frac{(N_0 / v_0)}{s + (1 / v_0)}$$
(3.b)

The zeroth order moment $M_0(t)$ that appears in Eq. (3.a) is obtained from its usual definition, and in this case is given by [32]:

$$M_{0}(t) = \int_{0}^{\infty} n(v,t) dv = \frac{2N_{0}}{2 + \beta_{0}N_{0}t}$$
(3.c)

Equations (3) are readily analytically solved, resulting:

$$\overline{n}(s,t) = \frac{4(N_0 / v_0)}{(2 + \beta_0 N_0 t)^2 \{s + 2 / [(2 + \beta_0 N_0 t) v_0]\}}$$
(4)

Applying the inverse Laplace transform in Eq. (4), one obtains:

$$n(v,t) = \mathcal{L}^{-1}[\overline{n}(s,t)] = \frac{4(N_0 / v_0)}{(2 + \beta_0 N_0 t)^2} \mathcal{L}^{-1} \left[\frac{1}{\{s + 2 / [(2 + \beta_0 N_0 t) v_0]\}} \right] = \frac{4(N_0 / v_0)}{(2 + \beta_0 N_0 t)^2} \exp\left[-\frac{2}{(2 + \beta_0 N_0 t)} \frac{v}{v_0} \right]$$
(5)

Assuming spherical particles, the volume distribution density is now related to its diameter distribution density through:

$$n_{D}(D,t) = n(v,t)\frac{dv}{dD} = \frac{\pi D^{2}}{2}n(v,t)$$
(6)

Therefore, introducing Eq. (5) into Eq. (6), it results in:

$$n_{\rm D}({\rm D},{\rm t}) = \frac{12(N_0 / D_0)(D / D_0)^2}{(2 + \beta_0 N_0 {\rm t})^2} \exp\left[-\frac{2}{(2 + \beta_0 N_0 {\rm t})} \left(\frac{D}{D_0}\right)^3\right]$$
(7)

2.1.2 Test-case 2

Similarly, the Laplace transform procedure of Eq. (1.a) for the test-case 2 is done, to obtain:

$$\mathcal{L}\left[\frac{\partial n(v,t)}{\partial t}\right] = \frac{\partial \overline{n}(s,t)}{\partial t}; \quad \mathcal{L}\left[\frac{\beta_1}{2} \int_0^v v n(v - \tilde{v},t) n(\tilde{v},t) d\tilde{v}\right] = -\beta_1 \overline{n}(s,t) \frac{\partial \overline{n}(s,t)}{\partial s};$$

$$\mathcal{L}\left[\beta_1 n(v,t) \int_0^\infty (v + \tilde{v}) n(\tilde{v},t) d\tilde{v}\right] = -\beta_1 M_0(t) \frac{\partial \overline{n}(s,t)}{\partial s} + \beta_1 M_1(t) \overline{n}(s,t)$$

$$(8.a-c)$$

The transformed differential equation for this case is given from Eqs. (8), in the form:

$$\frac{\partial \overline{n}(\mathbf{s},t)}{\partial t} + \beta_1 [\overline{n}(\mathbf{s},t) - \mathbf{M}_0(t)] \frac{\partial \overline{n}(\mathbf{s},t)}{\partial \mathbf{s}} = -\beta_1 \mathbf{M}_1(t) \overline{n}(\mathbf{s},t)$$
(9.a)

$$\overline{n}(s,0) = \frac{(N_0 / v_0)}{s + (1 / v_0)}$$
(9.b)

where, the zeroth and first-order moments, $M_0(t)$ and $M_1(t)$, respectively, in Eq. (9.a) are obtained as [32]:

$$M_{0}(t) = \int_{0}^{\infty} n(v,t) dv = N_{0} \exp(-\beta_{1} v_{0} N_{0} t); \quad M_{1}(t) = \int_{0}^{\infty} v n(v,t) dv = v_{0} N_{0}$$
(9.c,d)

Equation (9.a) is a hyperbolic-type differential equation and is analytically solved through the method of characteristics, to yield:

$$\overline{n}(s,t) = -\frac{v_0 N_0 \exp(-\beta_1 v_0 N_0 t)}{2[1 - \exp(-\beta_1 v_0 N_0 t)]} \left\{ \sqrt{\left[s + \frac{2 - \exp(-\beta_1 v_0 N_0 t)}{v_0}\right]^2 - \left[\frac{2}{v_0} \sqrt{[1 - \exp(-\beta_1 v_0 N_0 t)]}\right]^2 - \left[s + \frac{2 - \exp(-\beta_1 v_0 N_0 t)}{v_0}\right] \right\}}$$
(10)



The inverse Laplace transform of Eq. (10) is given by [32]:

$$n(v,t) = \mathcal{L}^{-1}[\overline{n}(s,t)] = -\frac{v_0 N_0 \exp(-\beta_1 v_0 N_0 t)}{2[1 - \exp(-\beta_1 v_0 N_0 t)]} \mathcal{L}^{-1} \left[\sqrt{\left[s + \frac{2 - \exp(-\beta_1 v_0 N_0 t)}{v_0}\right]^2 - \left[\frac{2}{v_0} \sqrt{[1 - \exp(-\beta_1 v_0 N_0 t)]}\right]^2 - \left[s + \frac{2 - \exp(-\beta_1 v_0 N_0 t)}{v_0}\right]^2 - \left[s +$$

$$\begin{bmatrix} v_0 \end{bmatrix} v_{\sqrt{1-\exp(-\beta_1 v_0 N_0 t)}} \begin{bmatrix} v_1 & v_1 & v_0 & v_0 \end{bmatrix} \begin{bmatrix} v_1 & v_1 & v_0 & v_0 \end{bmatrix}$$

Applying Eq. (6) to Eq. (11), the diameter distribution density is obtained as:

$$n_{\rm D}({\rm D},{\rm t}) = \frac{3(N_0 / D_0)\exp(-\beta_1 v_0 N_0 {\rm t})}{({\rm D} / D_0)\sqrt{[1 - \exp(-\beta_1 v_0 N_0 {\rm t})]}} \exp\left\{-[2 - \exp(-\beta_1 v_0 N_0 {\rm t})]\left(\frac{{\rm D}}{D_0}\right)^3\right\} I_1\left[2\sqrt{[1 - \exp(-\beta_1 v_0 N_0 {\rm t})]}\left(\frac{{\rm D}}{D_0}\right)^3\right]$$
(12)

2.1.3 Test-case 3

For this case, the only difference, concerning the test-case 1, is the Laplace transform of the first term on the right side of Eq. (1.a), which is given as follows:

$$\mathcal{L}\left[\frac{\partial[\sigma \upsilon n(\upsilon,t)]}{\partial \upsilon}\right] = -\sigma s \frac{\partial \overline{n}(s,t)}{\partial s}$$
(13)

Therefore, the transformed differential equation for this test-case 3 is obtained from Eqs. (2), in conjunction with Eq. (13), to yield:

$$\frac{\partial \overline{n}(\mathbf{s},t)}{\partial t} - \sigma \mathbf{s} \frac{\partial \overline{n}(\mathbf{s},t)}{\partial \mathbf{s}} = \frac{\beta_0}{2} \,\overline{n}^2(\mathbf{s},t) - \beta_0 \mathbf{M}_0(t) \overline{n}(\mathbf{s},t) \tag{14.a}$$

$$\overline{n}(s,0) = \frac{(N_0 / v_0)}{s + (1 / v_0)}$$
(14.b)

where the zeroth order moment $M_0(t)$ is the same as given by Eq. (3.c). Equation (14.a) is also analytically solved through the method of characteristics, to yield:

$$\overline{n}(s,t) = \frac{4(N_0 / v_0)e^{-\sigma t}}{(2 + \beta_0 N_0 t)^2 \{s + 2e^{-\sigma t} / [(2 + \beta_0 N_0 t)v_0]\}}$$
(15)

The inverse Laplace transform of Eq. (15) is:

$$n(v,t) = \mathcal{L}^{-1}[\overline{n}(s,t)] = \frac{4(N_0 / v_0)e^{-\sigma t}}{(2 + \beta_0 N_0 t)^2} \mathcal{L}^{-1} \left[\frac{1}{\{s + 2e^{-\sigma t} / [(2 + \beta_0 N_0 t)v_0]\}} \right] = \frac{4(N_0 / v_0)}{(2 + \beta_0 N_0 t)^2} \exp\left[-\frac{2e^{-\sigma t}}{(2 + \beta_0 N_0 t)} \frac{v}{v_0} - \sigma t \right]$$
(16)

In terms of diameter distribution density by applying Eq. (6) into Eq. (16), one has:

$$n_{\rm D}({\rm D},{\rm t}) = \frac{12(N_0 / D_0)(D / D_0)^2}{(2 + \beta_0 N_0 {\rm t})^2} \exp\left[-\frac{2e^{-\sigma {\rm t}}}{(2 + \beta_0 N_0 {\rm t})} \left(\frac{D}{D_0}\right)^3 - \sigma {\rm t}\right]$$
(17)

2.1.4 Test-case 4

For this case, the only difference, concerning the test-case 2, is the Laplace transform of the last term on the right side of Eq. (1.a), which is given as follows:

$$\mathcal{L}[R_0 n(v,t)] = R_0 \overline{n}(s,t) \tag{18}$$

Therefore, the transformed differential equation for this test-case 4 is obtained from Eqs. (9), in conjunction with Eq. (18), to yield:

$$\frac{\partial \overline{n}(\mathbf{s},\mathbf{t})}{\partial \mathbf{t}} - \beta_1 \left[\mathbf{M}_0(\mathbf{t}) - \left(\overline{n}(\mathbf{s},\mathbf{t}) \right) \right] \frac{\partial \overline{n}(\mathbf{s},\mathbf{t})}{\partial \mathbf{s}} = -\left(\beta_1 \mathbf{M}_1(\mathbf{t}) + \mathbf{R}_0 \right) \overline{n}(\mathbf{s},\mathbf{t})$$
(19.a)

$$\overline{n}(s,0) = \frac{(N_0 / v_0)}{s + (1 / v_0)}$$
(19.b)

where, the zeroth and first-order moments, $M_0(t)$ and $M_1(t)$, respectively, in Eq. (19.a) are shown below:

$$M_{0}(t) = \int_{0}^{\infty} n(v,t) dv = N_{0} \exp\left(\frac{\beta_{1} v_{0} N_{0} \left(\exp(-R_{0}t) - 1\right)}{R_{0}} - R_{0}t\right); \quad M_{1}(t) = \int_{0}^{\infty} v n(v,t) dv = v_{0} N_{0} \exp(-R_{0}t)$$
(20.a,b)

Equation (19.a) is also analytically solved through the method of characteristics, to yield:

$$\overline{n}(S,\widetilde{T}) = -\frac{1}{2\tilde{g}v_0}\tilde{T}N_0 \exp\left(\frac{\tilde{T}-1}{\theta}\right) \left\{\sqrt{S^2 - A^2} - S\right\}$$
(21)

Table 2. Results of comparison by both analytical and numerical Laplace transform inversion against the literature [29].

Test Case	$\tau = 0.25$	$\tau = 1.0$	$\tau = 2.0$	τ = 10.0	$\tau = 20.0$
1	0.00010	0.00358	0.00643	0.00684	0.00066
2	0.00578	0.02677	0.03443	-	-
3	0.00145	0.00248	0.00397	-	-
4	0.00201	0.00286	0.00757	-	-

where $\theta = R_0 / N_0 v_0 \beta_1$, $\tau = N_0 \beta_0 v_0 t$, $\tilde{T} = \exp(-\theta \tau)$, $\tilde{g} = 1 - \exp\left[\left(\tilde{T} - 1\right) / \theta\right]$, $S = s + (1 + \tilde{g})v_0$ and $A = 2v_0 \sqrt{\tilde{g}}$. The inverse Laplace transform of Eq. (21) is:

$$n(v,T) = -\frac{\tilde{T}N_0}{2\tilde{g}v_0} \exp\left(\frac{\tilde{T}-1}{\theta}\right) \exp\left[-(1+\tilde{g})v_0v\right] \mathcal{L}^{-1}\left[\sqrt{S^2-A^2}-S\right]$$
(22)

In terms of diameter distribution density by applying Eq. (6) into Eq. (16), one has:

$$n(v,T) = -\frac{\tilde{T}N_0}{v\sqrt{\tilde{g}}} \exp\left(\frac{\tilde{T}-1}{\theta}\right) \exp\left[-(1+\tilde{g})v_0v\right] I_1(2\sqrt{\tilde{g}}vv_0)$$
(23)

2.2 The numerical inverse Laplace Transforms

The Laplace transform has also the advantage that it solves problems directly, initial value problems without determining first a general solution and nonhomogeneous differential equations without solving first the corresponding homogeneous equations [33]. The Laplace transform of f(t) given by $F(s) = \int_{0}^{\infty} f(t)e^{-st}dt$ is a highly stable operation since variations in f(t) are averaged out in integration. Furthermore, the Laplace transform kernel, e^{-st} , converges asymptotically to zero when t tends to infinity, unless s is small, which implies that large variation on f(t) indicates small F(s) changes. However, difficulties may be encountered in the inversion step of the transformation because the inversion may not be possible through the usual techniques and the inverse Laplace transform is generally done numerically. There are over 100 methods available for the numerical inversion of Laplace transforms [34] based on the approximation of the inversion complex integral, PostWidder inversion formula, and methods based on the deformation of the contour of the Bromwich inversion integral [35].

Equations (4), (10), (15), and (21) are all non-linear in the s-variable. Particularly, for these test cases, it was possible to perform the inverse Laplace transform. However, difficulties may be found while using the Laplace transform to solve a differential equation in the inversion of the solutions from the Laplace domain to the time domain [36], and where the inverse transform cannot be determined analytically.

Alternatively, aiming at more general cases, in the present work, Eqs. (4), (10), (15), and (21) are numerically inverted through of the subroutine DINLAP from [37] at each time and spatial position of interest with a required tolerance of 10⁻⁴. The DINLAP is an optimized subroutine for high-performance computation from the thoroughly-tested IMSL Fortran Library and computes the inverse Laplace transform of a complex-valued function. The computation of the inverse Laplace transform is based on applying the epsilon algorithm to the complex Fourier series obtained as a discrete approximation to the inverse I[37]. Given a complex-valued transform F(s), the trapezoidal rule gives the approximation to the inverse transform.



Fig. 2. Comparison of $N(D, \tau)$ distribution for pure coagulation with constant kernel (test-case 1).





Fig. 3. Comparison of $N(D, \tau)$ distribution for pure coagulation with constant kernel and ratio (D/D₀) in the range [0,4] (test-case 1).



Fig. 4. Comparison of $N(D, \tau)$ distribution for pure coagulation with varying kernel (test-case 2).

3. Results and Discussions

The results of the numerical inversion for the four test cases were obtained in terms of diameter distribution. The codes were implemented in Fortran 90/95 programming language, which was run on a Pentium IV 1.70 GHz computer. For the numerical inversion of Eqs. (4), (10), (15), and (21), the subroutine DINLAP from the [37] was used with a tolerance of 10⁻⁴.

The comparison of results in the present work by both analytical and numerical Laplace transform inversion are compared against the results reported in the literature [29] for the solution of Eq. (1.a) by finite element method considering two different collisions mechanisms, first-order removal mechanism and the effect of simultaneous coagulation and growth, here referred to as test-case 1, 2, 3, and 4. The summary of the results can be observed in Table 2 in terms of mean absolute error. In Table 2 the comparison of numerical Laplace inversion against analytical Laplace transform inversion is suppressed since the calculated absolute error is less than 10⁻⁷.

The simplest form of Eq. (1.a) is considering the absence of growth and sources with constant collision mechanisms (case 1). Figure 2 shows the numerical inversion and exact results for the diameter density for the test-case 1 (pure coagulation with the constant kernel), using equally space elements in the range [0,3] of the ratio (D/D_0), for the dimensionless times ($\tau = \beta_0 N_0 t$), $\tau = 0$, 0.25, 1.0 and 2.0. An excellent agreement between the numerical inversion and exact solution was obtained, as well as with the results of [29]. Here, this is related to the diameter distribution in the dimensionless form: $N(D,\tau) = D_0 n_D(D,\tau)/N_0$. The precipitation and growth of particles are the result of several mechanisms, nucleation, molecular growth, and secondary processes such as aggregation and breakage. The phenomena of nucleation and growth are competitive, both consume the solute molecules and therefore the particle size is the result of this competition over time. In Fig. 2 it is noted that at time zero, the system precipitates many particles, increasing the population density of these particles. As time increased the phenomena of nucleation and growth happen simultaneously consuming the excess of these particles, providing their growth, and decreasing the density of the precipitated particles.





Fig. 5. Comparison of $N(D, \tau)$ distribution for both coagulation and particle growth with constant kernel (test-case 3).



Fig. 6. Comparison of N(D, τ) distribution for coagulation with varying kernel and removal rate (test-case 4).

Figure 3, using equally space elements in the range [0,4] of the ratio (D/D_0), shows a similar analysis as for Fig. 2, however, to demonstrate the performance of both techniques for long times ($\tau = 0$, 10.0, and 20.0), the distribution $N(D,\tau)$ is multiplied by the term $(\tau + 2)^2/4$. Also, an excellent agreement among the results is verified. In contrast to Fig. 2, in Fig. 3, considering long times, most of the molecules are already nucleated and the growth mechanism is dominant increasing both the density of the precipitated particles and the ratio (D/D_0).

Figure 4 shows a comparison of the $N(D,\tau)$ distribution for pure coagulation with varying kernel (test-case 2), also using equally space elements in the range [0,3] of the ratio (D/D_0) , for the dimensionless times using equally space elements in the range [0,3] of the ratio (D/D_0) , for the dimensionless times ($\tau = \beta_0 v_0 N_0 t$), $\tau = 0$, 0.25, 1.0 and 2.0. Once again, the three sets of results are in excellent agreement, which emphasizes the ability of the Laplace transform with numerical inversion in handling such types of problems. Compared to Fig. 2, in Fig. 4 the particle sizes are shifted faster than in case 1 due to the linear collision mechanism whereas in case 1 the collision is a constant.

Figure 5 shows the numerical inversion and exact results for the comparison of the $N(D,\tau)$ distribution for both coagulation and particle growth with constant kernel (test-case 3), using equally space elements in the range [0,3] of the ratio (D/D_0), for the dimensionless times ($\tau = \beta_0 N_0 t$), $\tau = 0$, 0.25, 1.0 and 2.0. As observed throughout the analysis an excellent agreement is verified among the sets of results. Compared to Fig. 2, in Fig. 5 the particle sizes are shifted faster than in case 1 due to the linear growth rate. Moreover, the linear growth rate condition causes the centrality of the density to be shifted as time is increased.

Figure 6 shows the comparison of $N(D,\tau)$ distribution for coagulation with varying kernel and removal rate (test-case 4), also using equally space elements in the range [0,3] of the ratio (D/D_0) , for the dimensionless times $(\tau = \beta_0 v_0 N_0 t)$, $\tau = 0$, 0.25, 1.0 and 2.0. Note that, an excellent agreement among the results is verified. Compared to Fig. 4, in Fig. 6 the particle size distributions are flattened due to the imposed particle removal rate.



4. Conclusion

The numerical inversion of the Laplace transform was successfully applied for the solution of the population balance equation. The studied cases considered different collision mechanisms, removal mechanisms, and growth. Because there is no universal method of numerical inversion that works well for all problems, the comparison of the numerical inversion in cases where the analytic inverse transform is known enables a more rational choice of the method to be used. The FORTRAN subroutine DINLAP performed the numerical inversion of the Laplace transform. The results generated were compared with data produced by the analytical solution, which have an excellent agreement. Thus, the method demonstrated to be an alternative tool for handling problems mathematically described by integro-differential equations, particularly for particulate systems. Considering the results presented in this work the population balance equation can also be solved using the Laplace transform technique with numerical inversion in problems where the same micro-scale processes. In such processes nucleation, growth, and agglomeration of particles can be present as in precipitation and crystallization processes

Author Contributions

C. da Silva Batista planned the scheme, initiated the project, and developed the code; H.K. Miyagawa performed the mathematical simulation and validated the results; E.N. Macêdo suggested the methodology for conducting the project; J.N.N. Quaresma developed the mathematical modeling and examined the theory validation. H.R.B. Orlande developed the code and conducted the analysis. The manuscript was written through the contribution of all authors. All authors discussed the results, reviewed, and approved the final version of the manuscript.

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Conflict of Interest

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Data Availability Statements

The datasets generated and/or analyzed during the current study are available from the corresponding author on reasonable request.

Nomenclature

- D Particle diameter [µm]
- D_0 Initial particle diameter [µm]
- $I_{v}(v,t)$ Rate of change of volume by mass transfer between particles and fluid
- Perturbation kernel Κ.
- n(v,t) Size distribution density function [μ m⁻³.cm⁻³]
- n(D,t) Size distribution density function as a function of diameter [µm⁻¹.cm⁻¹]
- $N(D, \tau)$ Dimensionless size distribution density function
 - N₀ Total number of particle at t = 0 [cm⁻³]
 - R₀ Removal Rate [cm³.s⁻¹]

- Laplace transform domain s
- S Net rate of addition or removal of particles in the system [cm³.s⁻¹]
- υ Particle volume [cm³]
- Importance weights w

Greek Letters

- Coagulation coefficient β
- Constant aggregation coefficient [cm³.s⁻¹] β_0
- Linear aggregation coefficient [cm³.s⁻¹] β_1
- Dimensionless time

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